

# Star-Struck by Fixed Embeddings

## Modern Crossing Number Heuristics

GD '21

Joint work with Markus Chimani and Tilo Wiedera

Max Ilsen, University of Osnabrück

September 15, 2021

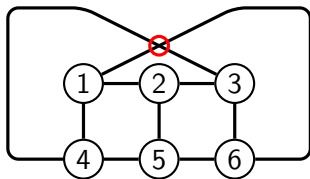
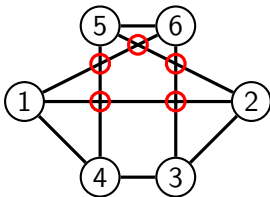
`max.ilsen@uos.de`

# Crossing Number Problem

- Motivation
- Algorithms
- Evaluation
- Conclusion

**Given:** Graph  $G$

**Task:** Find minimum number of edge crossings in any drawing of  $G$

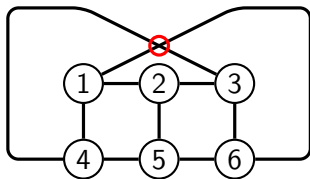
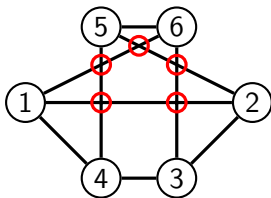


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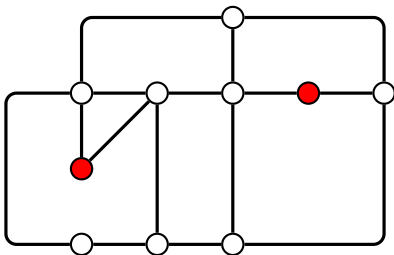
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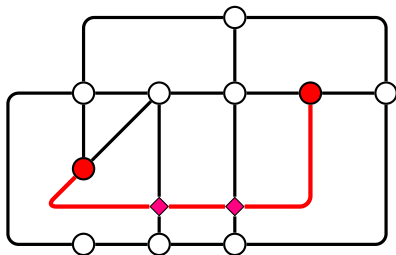


NP-hard even in restricted settings  
→ Let's evaluate some heuristics!

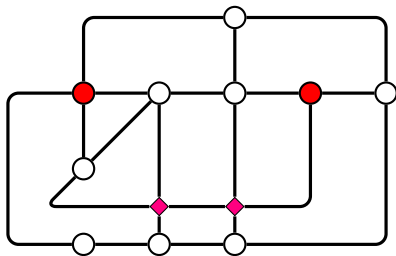
→ compute planar subgraph, insert remaining edges iteratively



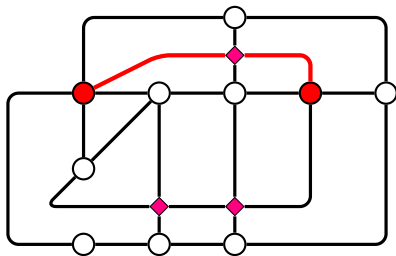
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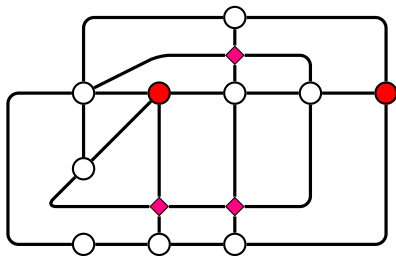
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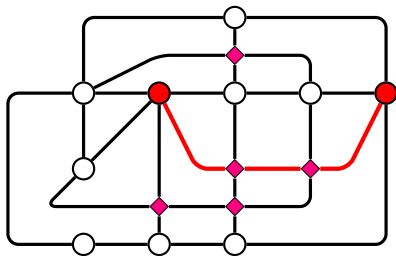


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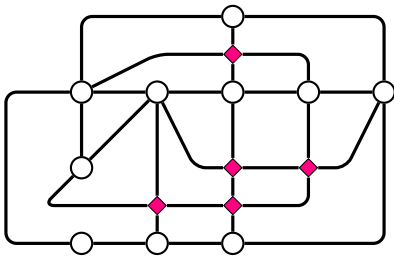




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### Edge Insertion:

- **fixed** embedding (Batini, Talamo, and Tamassia 1984)
- **variable** embedding (Gutwenger, Mutzel, and Weiskircher 2005)
- **multiple** edge insertion (Chimani and Hlinený 2011)

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### Post-Processing:

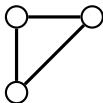
- **all**: remove and reinsert every edge at the end  
(Gutwenger and Mutzel 2003)
- **inc**: perform **all** after each edge insertion  
(Chimani and Gutwenger 2012)

# Chordless Cycle Method

## Heuristic #2

- Motivation
- o Algorithms
- Evaluation
- Conclusion

→ compute chordless cycle, insert partial stars connected to it

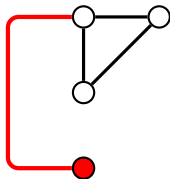


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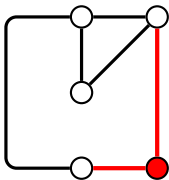


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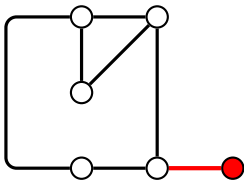


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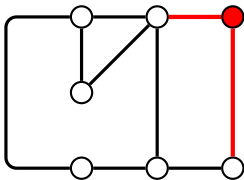


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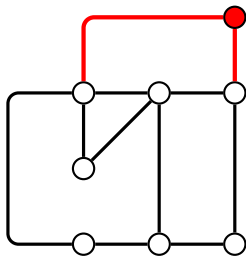


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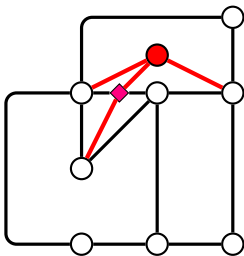


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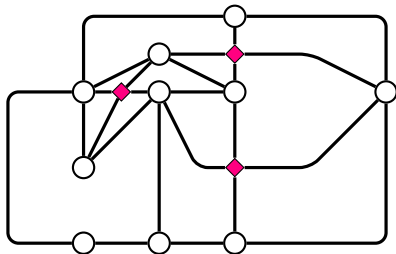


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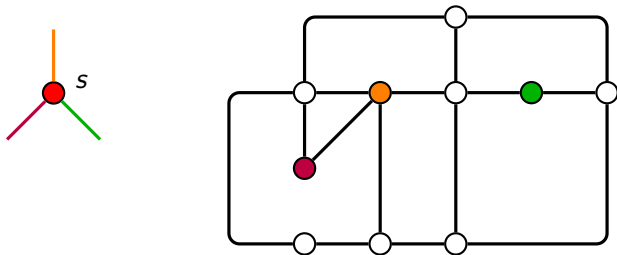


# Star Insertion (Fixed Embedding)

- Motivation
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**Given:** Planar graph  $G$ , embedding  $\Pi$  of  $G$ , **star**  $s$  not yet in  $G$

**Task:** Insert  $s$  into  $\Pi$  s.t. the number of crossings in  $\Pi$  is minimized

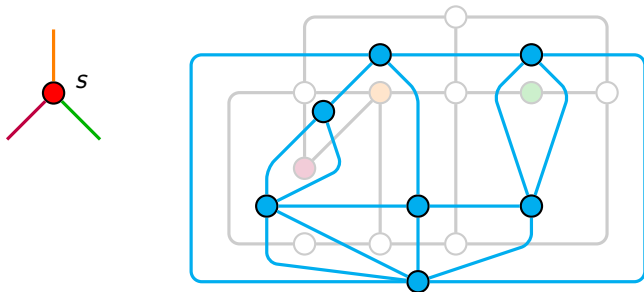


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→ add up distance values from breadth-first-searches in dual graph



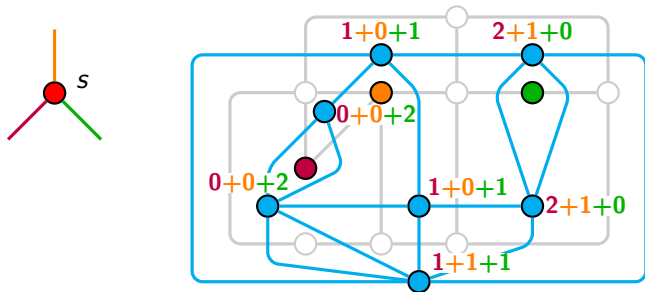
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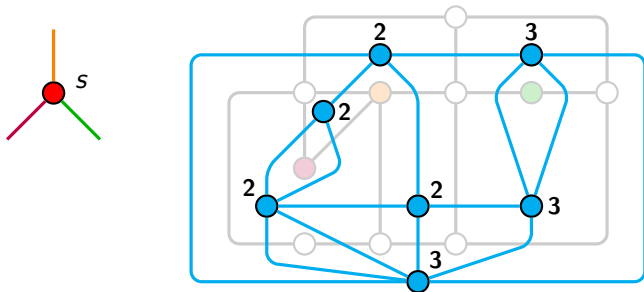


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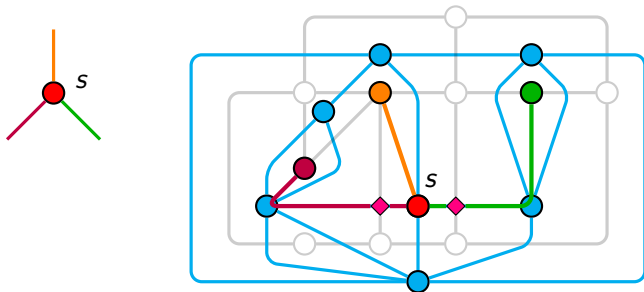
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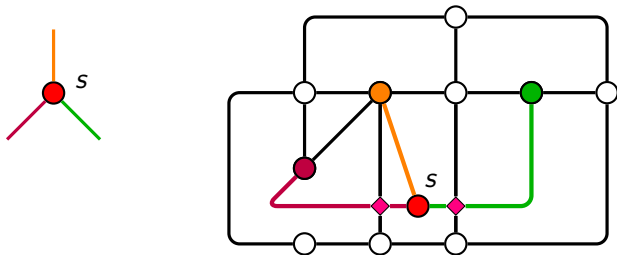
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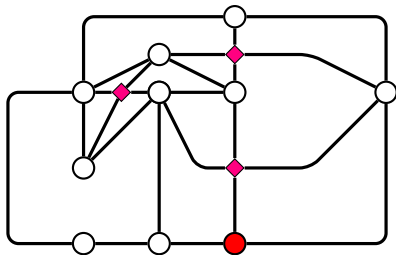


# Star Reinsertion Method

## Post-Processing

- Motivation
- Algorithms
- Evaluation
- Conclusion

→ create initial planarization, remove and reinsert stars until no reinsertion can decrease number of crossings

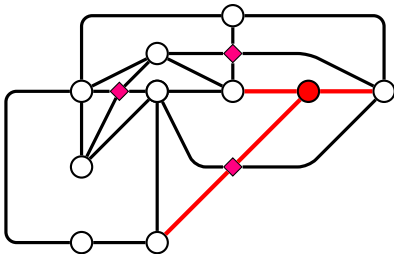


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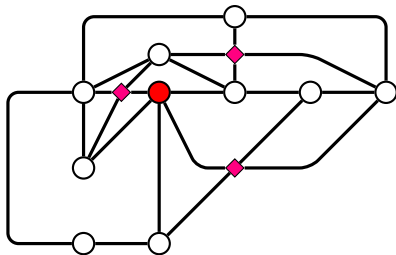


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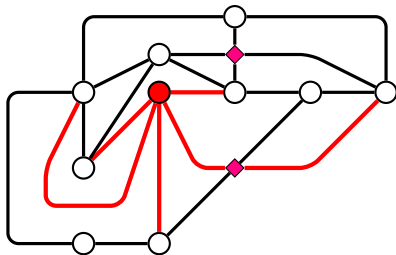


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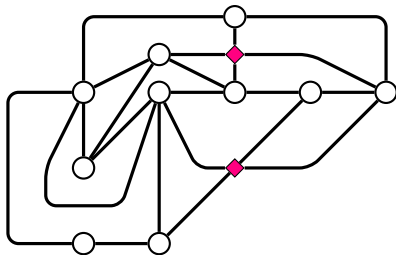


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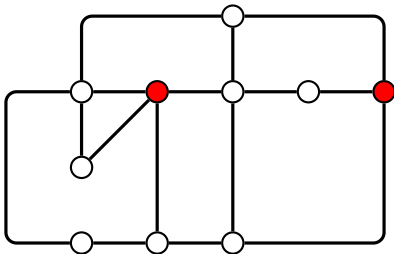


# Mixed Insertion Method

## Heuristic #3: Our Own Approach

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→ compute planar subgraph, insert remaining edges via star insertion of their endpoints (if possible)

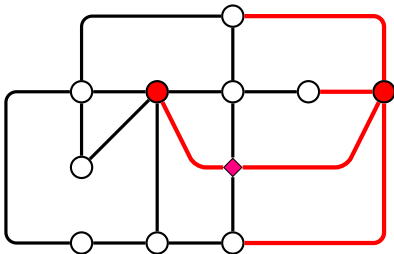


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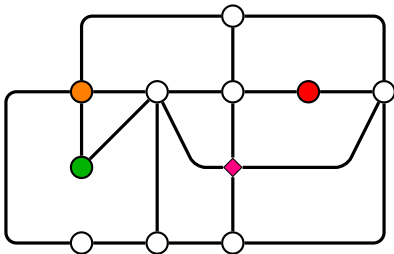


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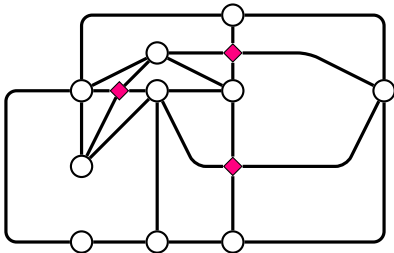


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## Setup:

- C++ (GCC 8.3.0), Open Graph Drawing Framework (OGDF)
- single physical processor of a Xeon Gold 6134 CPU (3.2 GHz)
- memory limit of 4 GB, no time limit

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<sup>1</sup>Chimani and Gutwenger 2009

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## Pre-Processing:

- non-planar core reduction<sup>1</sup>
- precomputed planar subgraph and chordless cycle

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<sup>1</sup>Chimani and Gutwenger 2009

Name	$\geq 25$ vertices in NPC	
	#	$ V(G) $
<b>Rome</b>	3668	25–58
<b>North</b>	106	25–64
<b>Webcompute</b>	75	25–112
<b>Expanders</b>	240	30–100
<b>Circuit-Based</b>	45	26–3045
<i>ISCAS-85</i>	9	180–3045
<i>ISCAS-89</i>	24	60–584
<i>ITC-99</i>	12	26–980

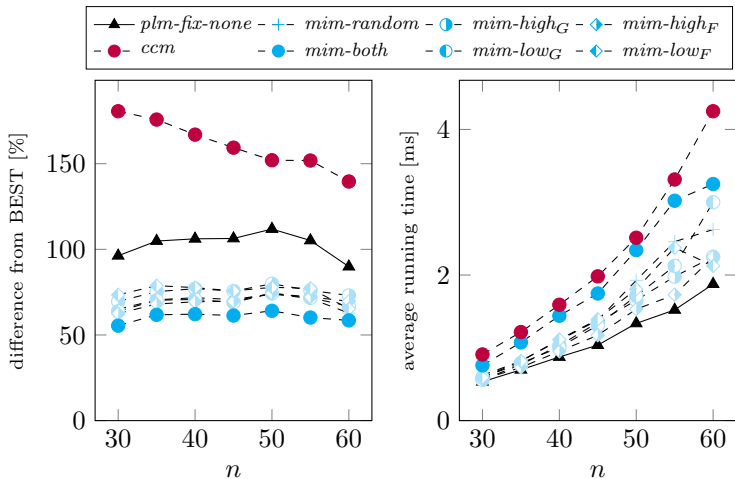
Name	all instances	
	#	$ V(G) $
<b>Complete</b>	46	5–50
<b>Complete-Bip.</b>	666	10–80
<b>KnownCR</b>	1946	9–250
$C \square C$	251	9–250
$G \square P$	893	15–245
$G \square C$	624	15–250
$P(-, -)$	178	10–250



# Fast Heuristics

Rome

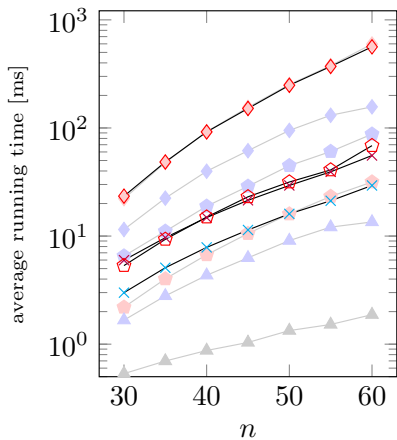
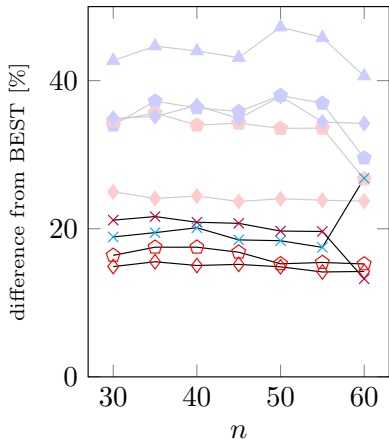
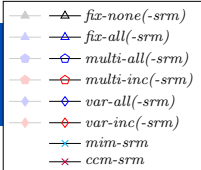
Motivation  
Algorithms  
Evaluation  
Conclusion



# Star Reinsertion Method

## Rome

Motivation  
Algorithms  
○ Evaluation  
Conclusion



- **fixed star reinsertion** beats variable edge insertion
- **mixed insertion method:** best quality among fast heuristics
- ***srm*-post-processing** improves all heuristics

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- easy improvements via removal of **non-simple crossings**

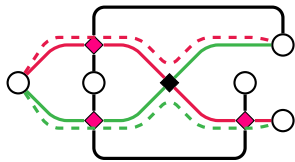
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**Thank you! Any questions?**

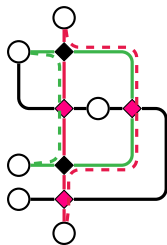
# Non-simple Crossings

## Removal

- Motivation
- Algorithms
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$\alpha$ -crossing  
adjacent edges

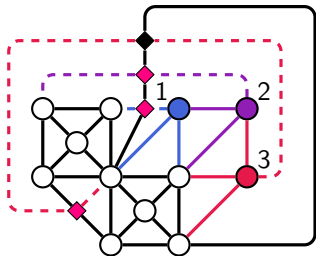


$\beta$ -crossing  
two edges, multiple crossings

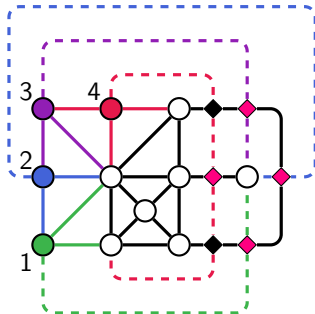
# Non-simple Crossings

Creation

Motivation  
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$\alpha$ -crossing



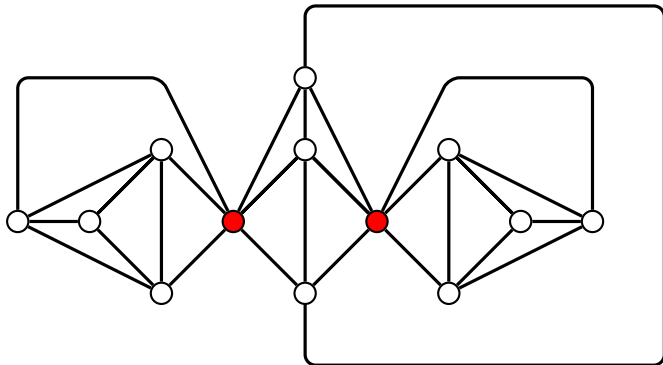
$\beta$ -crossing

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## Heuristic #3: Our Own Approach

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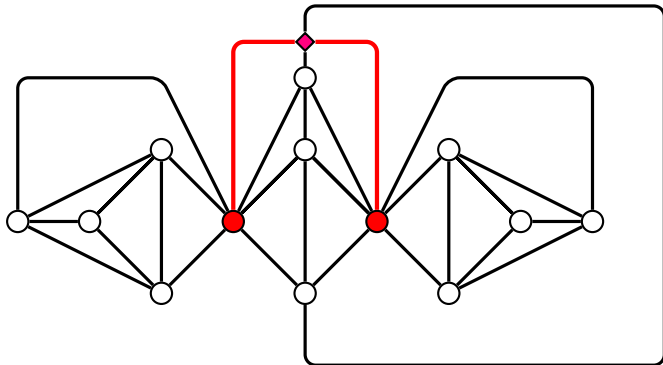


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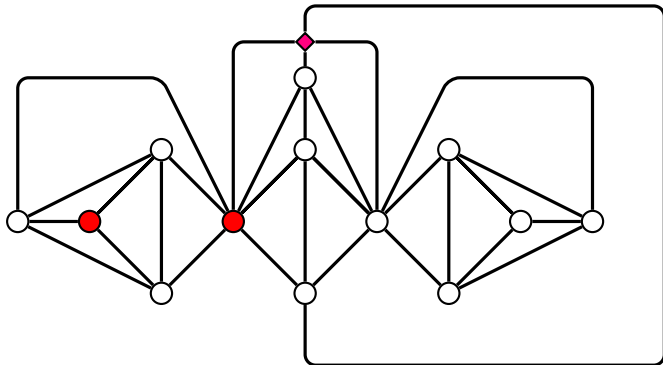
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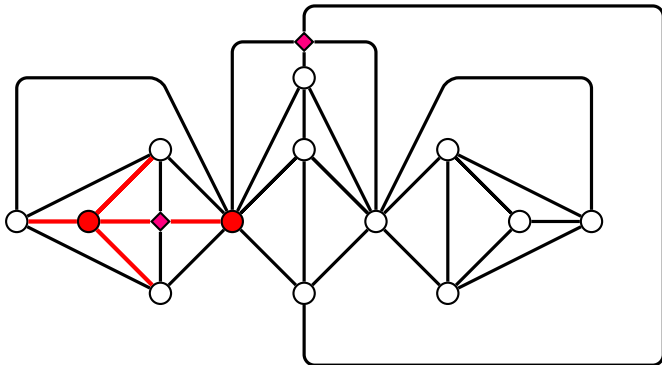


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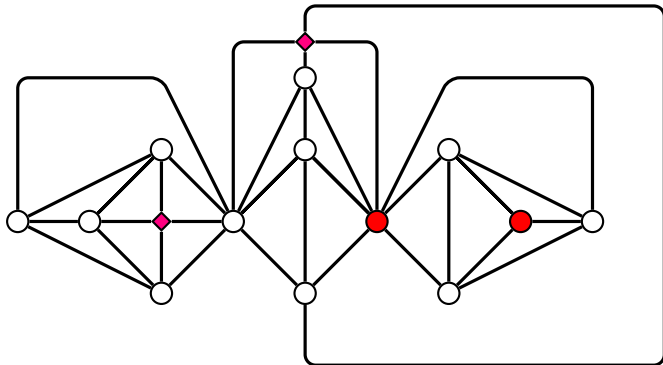


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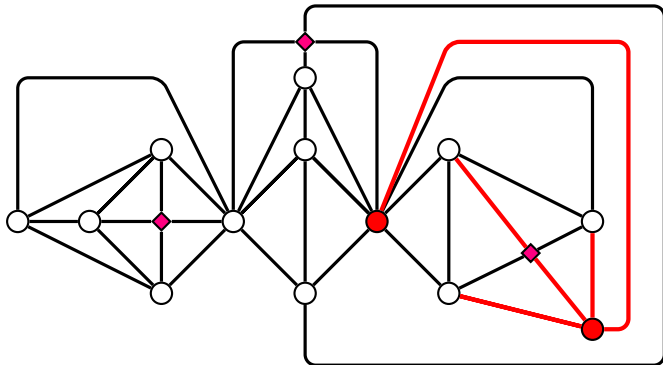


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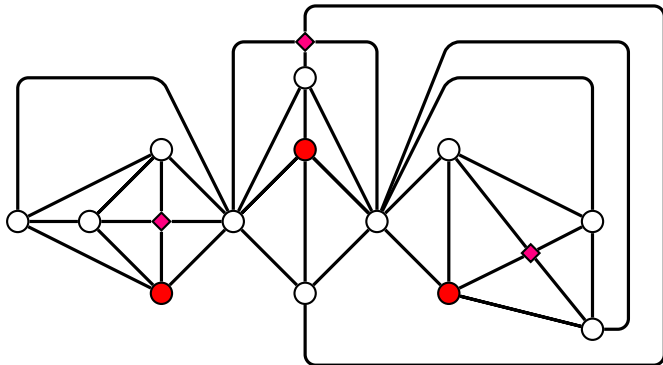


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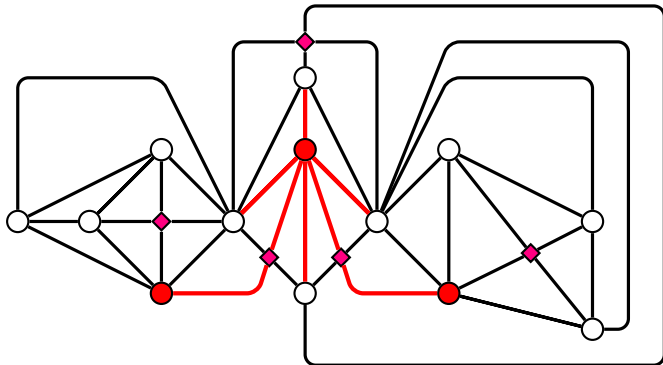
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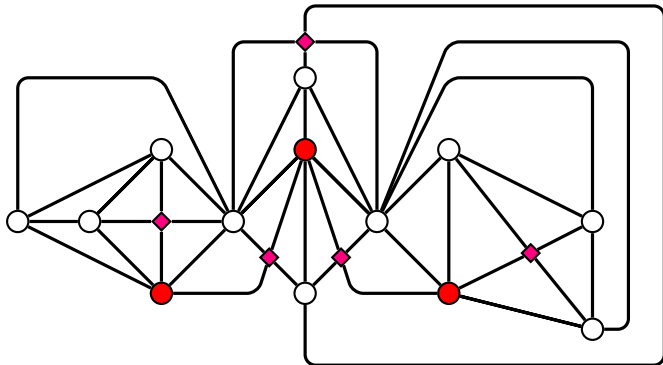


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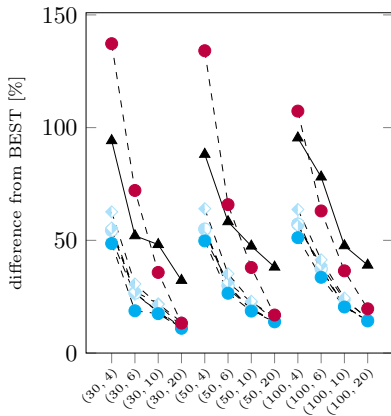
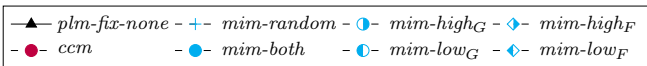




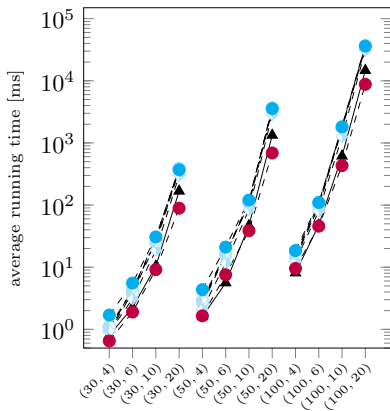
# Fast Heuristics

## Expanders

- Motivation
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$(|V(G)|, \delta)$

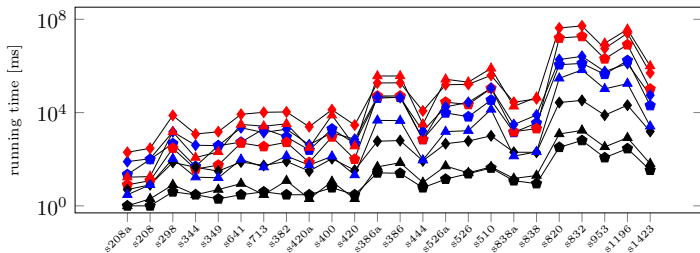
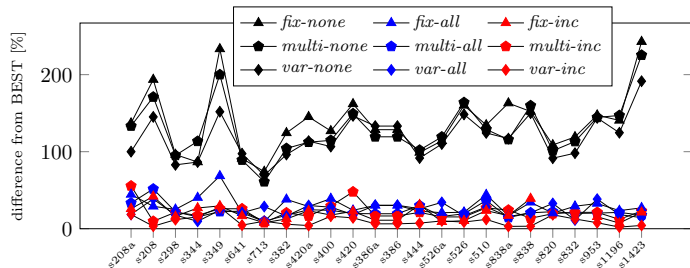


$(|V(G)|, \delta)$

# Planarization Method

## ISCAS-89

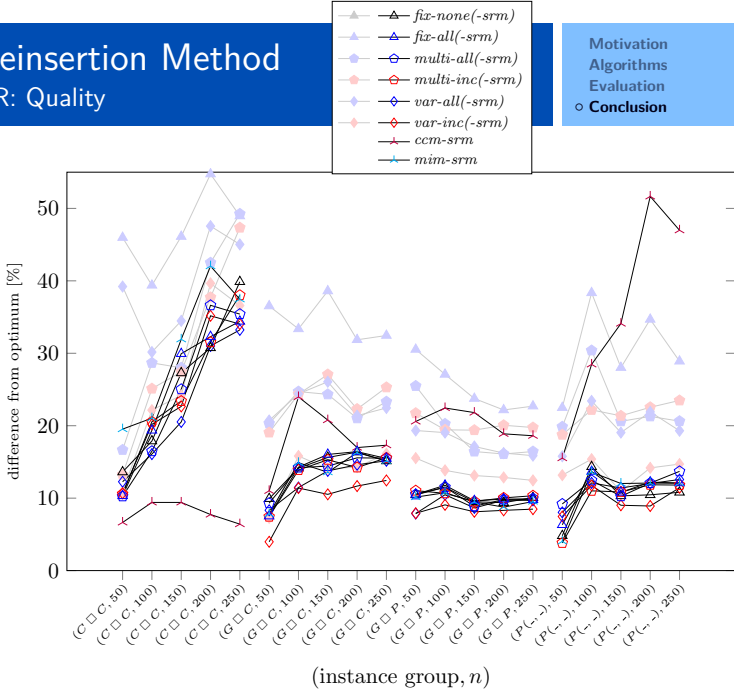
- Motivation
- Algorithms
- Evaluation
- Conclusion



# Star Reinsertion Method

KnownCR: Quality

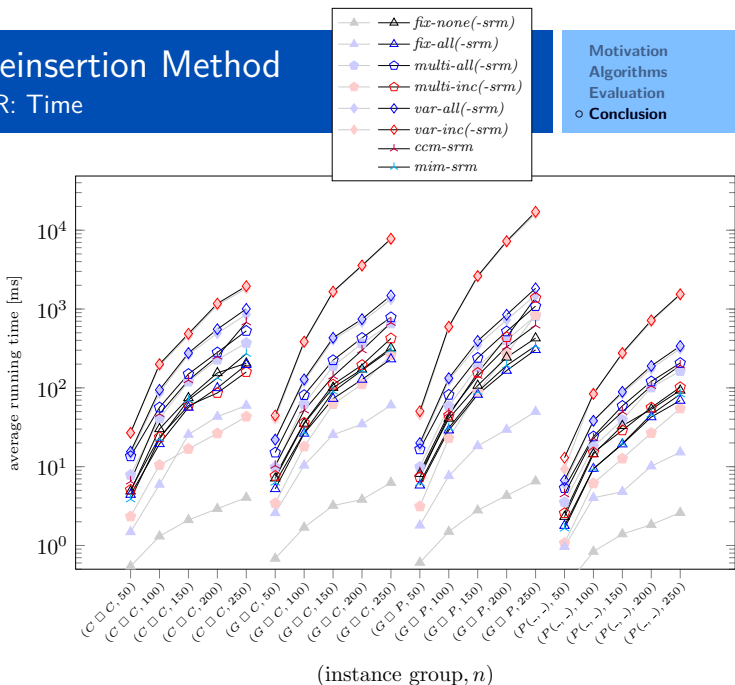
Motivation  
Algorithms  
Evaluation  
○ Conclusion



# Star Reinsertion Method

KnownCR: Time

Motivation  
Algorithms  
Evaluation  
○ Conclusion

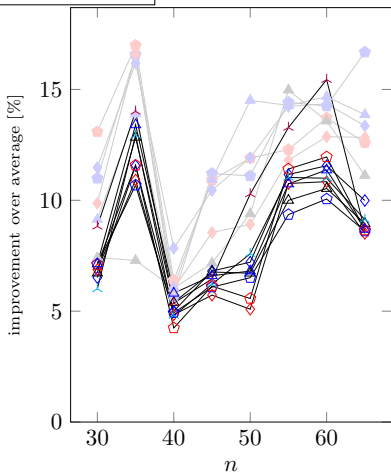
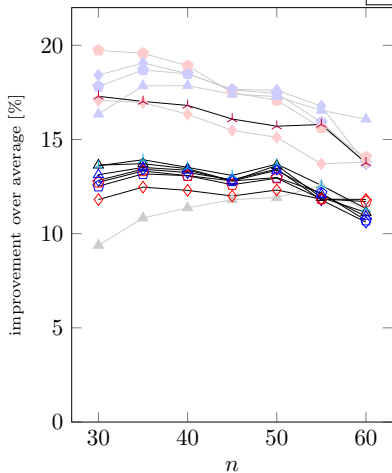


# Random Permutations

## Improvement: Rome and North

Motivation  
Algorithms  
Evaluation  
○ Conclusion

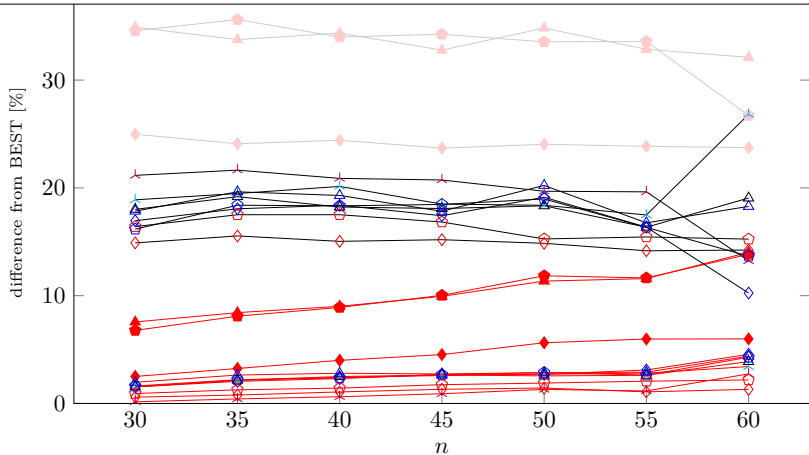
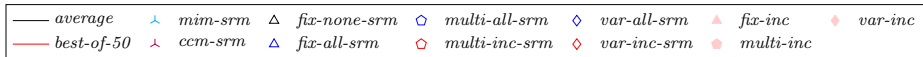
- ▲ *fix-none(-srm)*
- ▲ *fix-all(-srm)*
- *multi-all(-srm)*
- *multi-inc(-srm)*
- ◆ *var-all(-srm)*
- ◆ *var-inc(-srm)*
- × *ccm-srm*
- ◆ *mim-srm*



# Random Permutations

Rome

Motivation  
Algorithms  
Evaluation  
○ Conclusion



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